

TCM

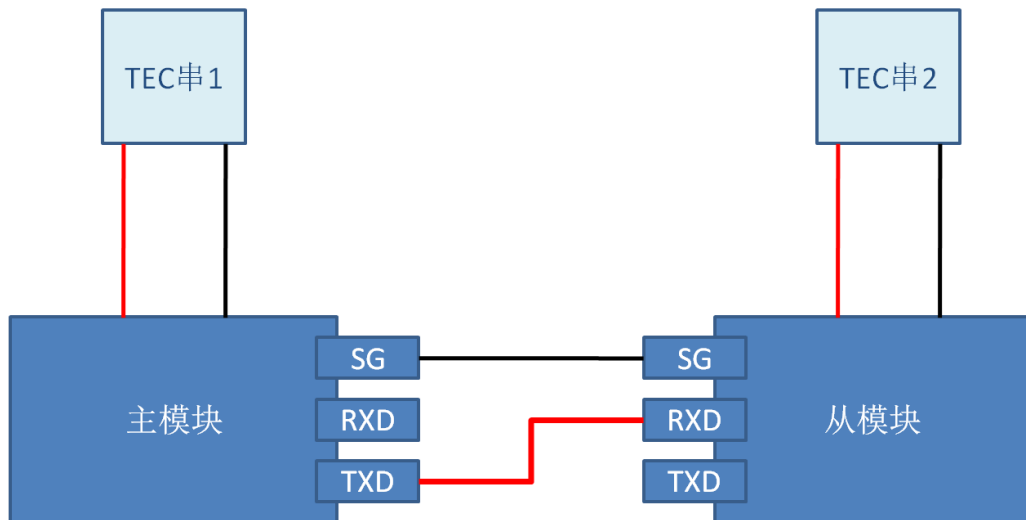
1. RS232

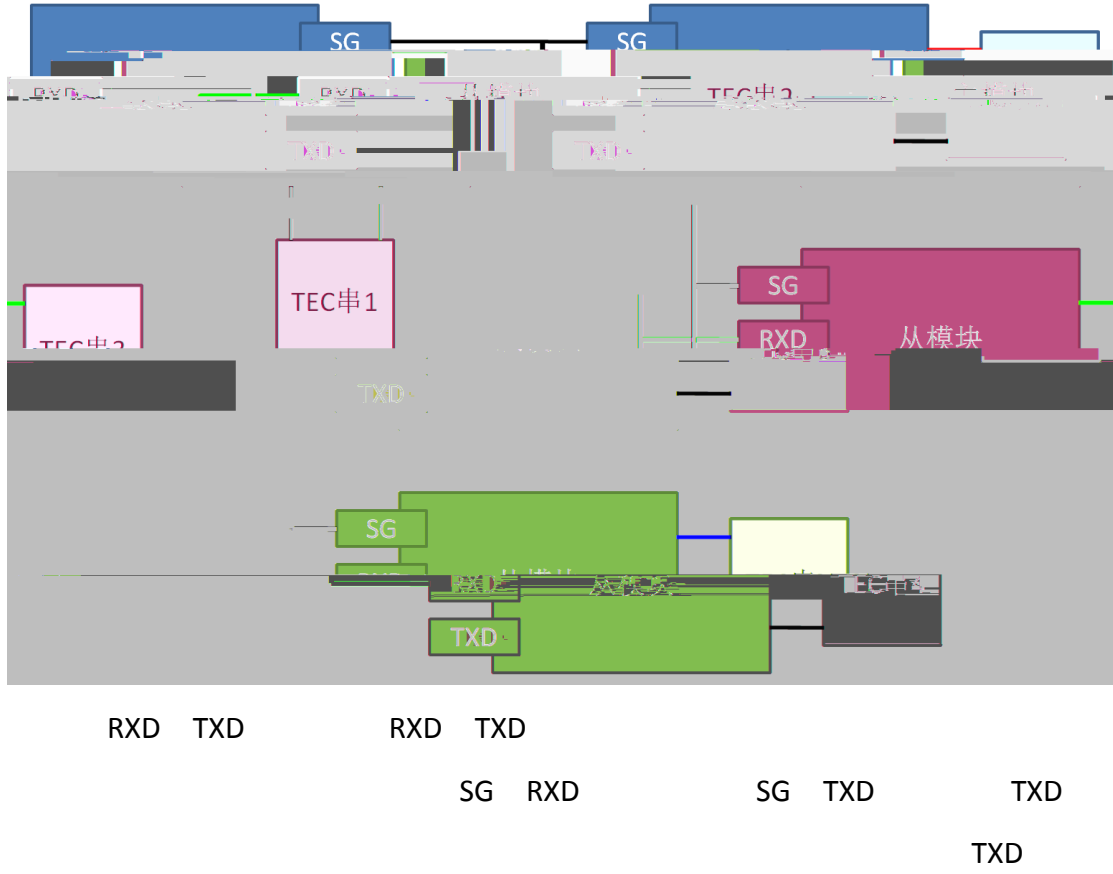
2.

TEC

3.

TEC





| | |
|--|--|
| | |
| | <ol style="list-style-type: none"> 1. 1 TCM 2. 1 UIM 3. 1 4. |
| | <ol style="list-style-type: none"> 1. 2. 1 3. TC1 Menu > PID > PID Cal Slave 4. Slave |
| | <ol style="list-style-type: none"> 1. 2. 3. |
| | <ol style="list-style-type: none"> 1. PID Td Td 0 2-10 |

1

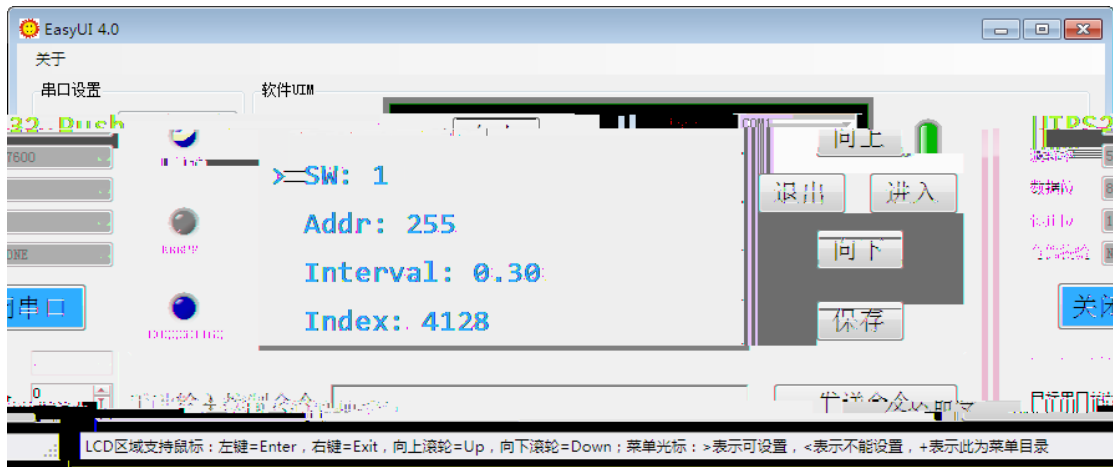
TEC

2

TEC

TEC

Push



UIRS232

| | |
|----------|--|
| | |
| SW | |
| Addr | |
| Interval | |
| Index | |

SW

Addr

1

255

255

255

255

Interval

0.05 0.3 1

Index

1 4 1-255 1

16 2 Index 32 4

4 4

0

Index 4

$$\text{Index} = \text{Index4} \times 256^3 + \text{Index3} \times 256^2 + \text{Index2} \times 256 + \text{Index1}$$

2

TC1:TCSW TC1:TCPIDDUTYRATIO

2

Index4 Index3

0

$$\text{Index} = 16 \times 256 + 32 = 4128$$

Index 4128

| | | |
|---------------------|----|-----|
| TC1: TCACTUALTEMP | 1 | |
| TC1: TCADJUSTTEMP | 2 | |
| TC1:TCSW | 16 | |
| TC1:TCOE | 17 | |
| TC1:LED | 18 | |
| TC1:TCACTUALVOLTAGE | 24 | |
| TC1:TCACTUALCURRENT | 25 | |
| TC1:TCPIDDUTYRATIO | 32 | PID |

PCB:TMACTUALTEMP

